

Modulating damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 0.8 m²
- Nominal torque 4 Nm
- Nominal voltage AC/DC 24 V
- · Control Modulating DC (0)2...10 V
- Position feedback DC 2...10 V
- Running time motor 2.5 s



Technical data sheet

Technical data			
Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
	Power consumption in operation	13 W	
	Power consumption in rest position	2 W	
	Power consumption for wire sizing	23 VA	
	Power consumption for wire sizing note	Imax 20 A @ 5 ms	
	Connection supply / control	Cable 3 m, 4 x 0.75 mm ² (halogen-free)	
	Parallel operation	Yes (note the performance data)	
Functional data	Torque motor	Min. 4 Nm	
	Positioning signal Y	DC 010 V	
	Positioning signal Y note	Input impedance 100 kΩ	
	Operating range Y	DC 210 V	
	Position feedback U	DC 210 V	
	Position feedback U note	Max. 0.5 mA	
	Position accuracy	±5%	
	Direction of rotation motor	Can be selected with switch 0/1	
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1	
		(cw rotation)	
	Manual override	Gear disengagement with push-button, can be	
		locked	
	Angle of rotation	Max. 95°	
	Angle of rotation note	can be limited on both sides with adjustable	
	_	mechanical end stops	
	Minimum angle of rotation	Min. 30°	
	Running time motor	2.5 s / 90°	
	Adaption setting range	manual (automatic on first power-up)	
	Override control	MAX (maximum position) = 100%	
		MIN (minimum position) = 0%	
		ZS (intermediate position, AC only) = 50%	
	Sound power level motor	52 dB(A)	
	Spindle driver	Universal spindle clamp 826.7 mm	
	Position indication	Mechanically, pluggable	
Safety	Protection class IEC/EN	III Safety extra-low voltage	
	Protection class UL	UL Class 2 Supply	
	Degree of protection IEC/EN	IP54	
	Degree of protection NEMA/UL	NEMA 2, UL Enclosure Type 2	
	EMC	CE according to 2004/108/EC	
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
	Certification UL	cULus according to UL 60730-1A, UL 60730-2- 14 and CAN/CSA E60730-1:02	
	Mode of operation	Type 1	
	Rated impulse voltage supply / control	0.8 kV	
	Control pollution degree	3	
	Ambient temperature	-3040°C	
	Ambient temperature note	Caution: +40+50°C utilisation possible only	
		under certain restrictions. Please contact your	
	Non-energing toppy	supplier.	
	Non-operating temperature	-4080°C	

Damper actuator, Modulating, AC/DC 24 V, 4 Nm, Running time motor 2.5 s



Technical data

 Safety
 Ambient humidity
 95% r.h., non-condensing

 Maintenance
 Maintenance-free

 Weight
 Weight approx.
 0.98 kg

Safety notes



- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaption is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaption push-button once).
- When calculating the torque required, the specifications supplied by the damper manufacturers (cross-section, construction, place of installation), and the ventilation conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

The actuator is connected with a standard modulating signal of DC 0 ... 10V and travels to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0 ... 100% and as slave control signal for other actuators.

Direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with a universal mounting bracket to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Adjustable angle of rotation

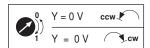
Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of 30° must be allowed for.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaption, which is when the operating range and position feedback adjust themselves to the mechanical setting range.

The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics.

The actuator then moves into the position defined by the positioning signal.



Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal.



Electrical installation

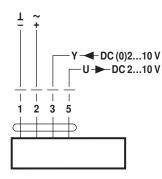


Notes

- · Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams

AC/DC 24 V, modulating



Cable colours:

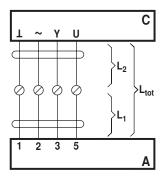
1 = black

2 = red

3 = white

5 = orange

Signal cable lengths



L ₂	$L_{tot} = L_1 + L_2$	
1/∼	AC	DC
0.75 mm ²	≤30 m	≤5 m
1.00 mm ²	≤40 m	≤8 m
1.50 mm ²	≤70 m	≤12 m
2.50 mm ²	≤100 m	≤20 m

A = actuator

C = control unit

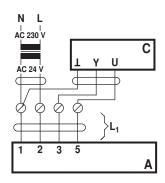
L1 = actuator connecting cable

L2 = customer cable

Ltot = maximum signal cable length

Note:

In the event of several actuators switched in parallel, the maximum signal cable length is to be divided by the number of actuators.



A = actuator

C = control unit

L1 = actuator connecting cable

Note:

If supply and data line are handled separately, then no special limitations apply for the installation.

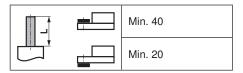


Installation notes

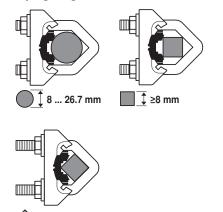
Negative torque Max. 50% of the torque (Caution: Application possible only with restrictions. Please contact your supplier.)

Dimensions [mm]

Spindle length



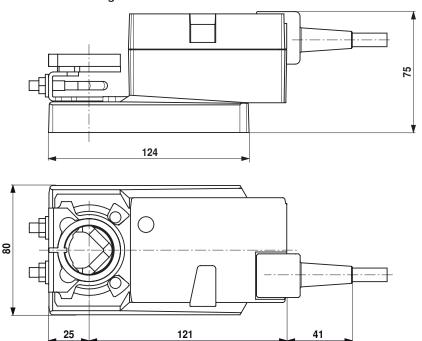
Clamping range

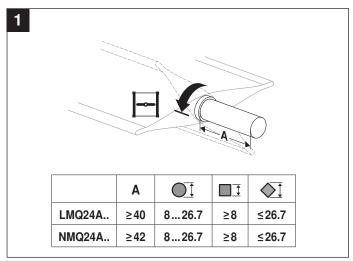


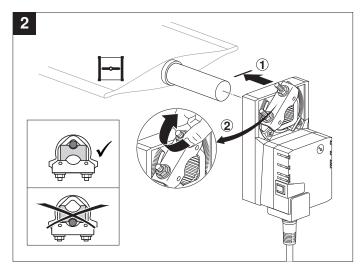
When an auxiliary switch or a feedback potentiometer is used, see «Accessories».

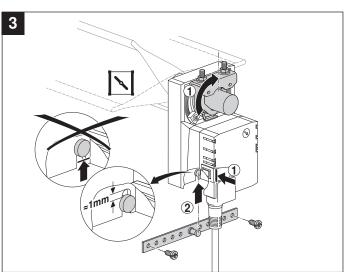
≤26.7 mm

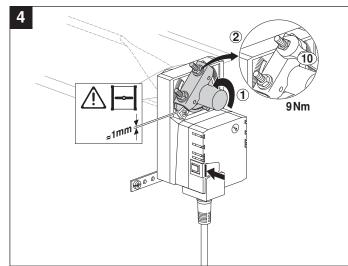
Dimensional drawings

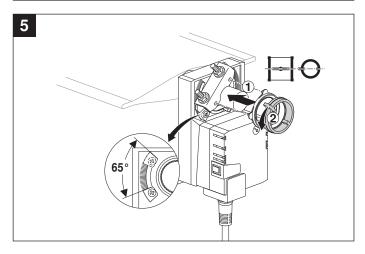


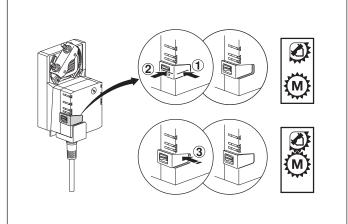


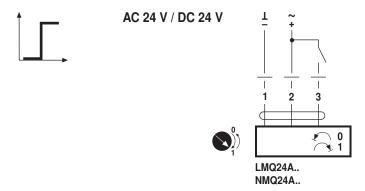






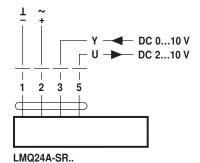








AC 24 V / DC 24 V



LMQ24A-MF.. LMQ24A-SRV-ST NMQ24A-SR.. NMQ24A-MF.. NMQ24A-SRV-ST

2/2